

Algorithms - Spring '25

MSSP




Recap

- HW posted, due next wed
↳ MST & Shortest Paths
- Next week's readings are up
- Algorithm's visualizer:
demo]
- End time note: please stop
me if I do go over!

Shortest paths so far

Key: relaxing tense edges $d(v) > d(u) + w(u,v)$



Time to compute shortest path tree rooted at any $s \in V$.

• IF your graph is unweighted:

BFS: $O(V + E)$

• IF your graph is a DAG:

Top sort + DP: $O(V + E)$

• IF no negative edges:

Dijkstra: $O(E \log V)$

Dijkstra: Saw 2 versions.

One of them works on negative edges (no cycles).

DJKSTRA(s):

INITSSSP(s)

INSERT(s, 0)

while the priority queue is not empty

$u \leftarrow \text{EXTRACTMIN}()$

for all edges $u \rightarrow v$

if $u \rightarrow v$ is tense

RELAX($u \rightarrow v$)

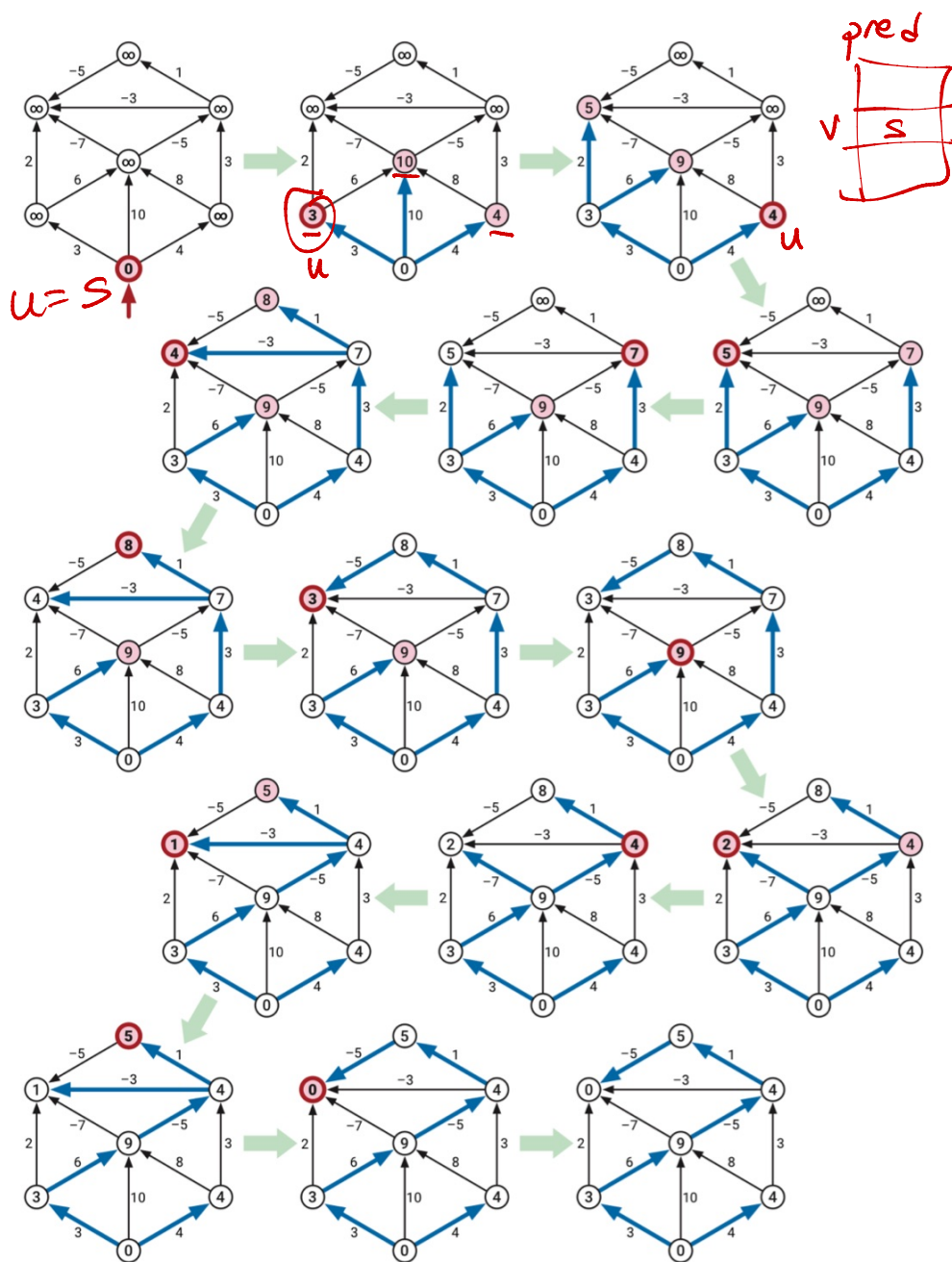
if v is in the priority queue

DECREASEKEY($v, \text{dist}(v)$)

else

INSERT($v, \text{dist}(v)$)

Figure 8.11. Dijkstra's algorithm.



worst case!
exp time

If negative edges and (potentially)
negative cycles:

Bellman-Ford

Runtime:

$O(VE)$

BELLMANFORD(s)

INITSSSP(s)

repeat $V - 1$ times

for every edge $u \rightarrow v$

if $u \rightarrow v$ is tense

RELAX($u \rightarrow v$)

for every edge $u \rightarrow v$

if $u \rightarrow v$ is tense

return "Negative cycle!"

- or -

BELLMANFORDFINAL(s)

$dist[s] \leftarrow 0$

for every vertex $v \neq s$

$dist[v] \leftarrow \infty$

for $i \leftarrow 1$ to $V - 1$

for every edge $u \rightarrow v$

if $dist[v] > dist[u] + w(u \rightarrow v)$

$dist[v] \leftarrow dist[u] + w(u \rightarrow v)$

Multiple-Source Shortest Paths (MSSP)

MSSP(G):

for each pair $u, v \in G$:

Compute shortest $u \rightsquigarrow v$

Compute shortest $v \rightsquigarrow u$

Store in $\text{Dist}[u, v]$ +

$\text{Dist}[v, u]$

Dist:

	1	2	...	u	v
1	0				
2		0			
...					
u				0	
v					0

Lookup:

$O(1)$

Computing MSSPs:

First attempt: [for each vertex v
Run SSSP(v)]

Runtime : $O(V \times (\text{SSSP alg}))$

• if unweighted or a DAG, SSSP was

$$O(V+E) \Rightarrow O(V(V+E))$$

• no negative edge weights, Dijkstra was

$$O(E \log V) \Rightarrow O(VE \log V) = O(V^3 \log V)$$

• Bellman-Ford was $O(VE)$

$$\Rightarrow O(V^2 E) = O(V^4)$$

\uparrow
 $E = V^2$

Side question:

Since negative edges are bad, why can't we just re-weight?

Idea: Increase all edge weights by some amount, so all positive.

Doesn't work?

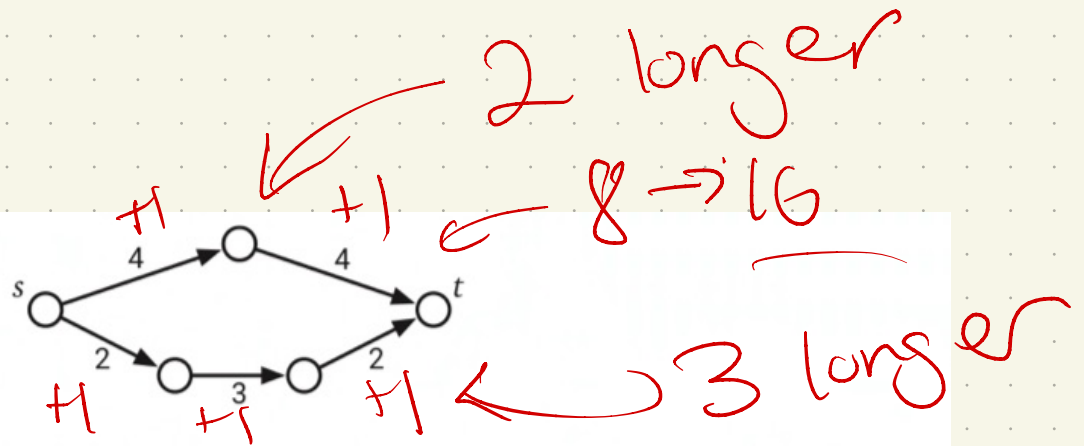


Figure 9.1. Increasing all the edge weights by 2 changes the shortest path from s to t .

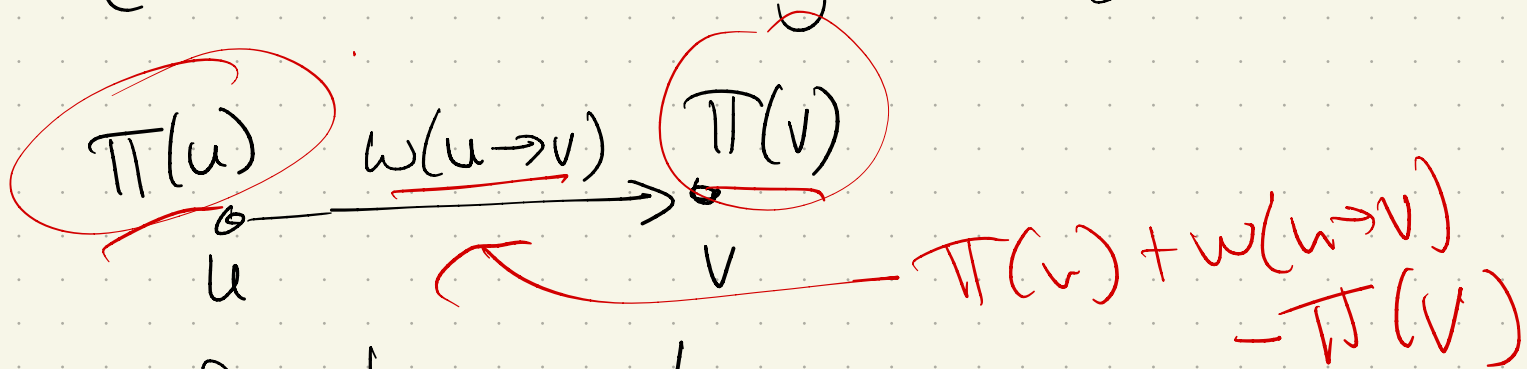
Why?

not reweighting paths the same amount

Another idea (that works):

Suppose each v has a price attached,
 $\pi(v)$.

(Still have edge weights.)



Define a new function w'_e :

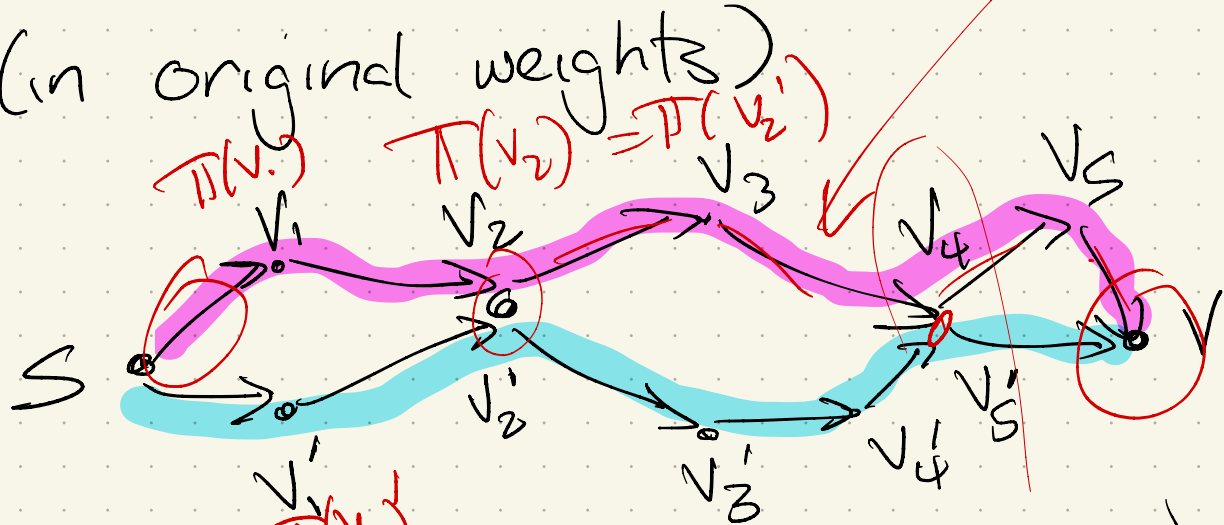
$$w'(u \rightarrow v) = \pi(u) + w(u \rightarrow v) - \pi(v)$$

Claim: Shortest path is unchanged!
all paths stay in same "order"

Claim: under w' , shortest paths are the same as under w .

Why? Consider 2 $s \rightsquigarrow v$ paths:

(in original weights)



Weights: $\pi(v_i)$
 purple: $w(s \rightarrow v_1) + w(v_1 \rightarrow v_2) + \dots + w(v_5 \rightarrow v)$

Purple path after reweighting:

$$\left[\pi(s) + w(s \rightarrow v_1) - \pi(v_1) \right] + \left[\pi(v_1) + w(v_1 \rightarrow v_2) - \pi(v_2) \right] + \dots$$

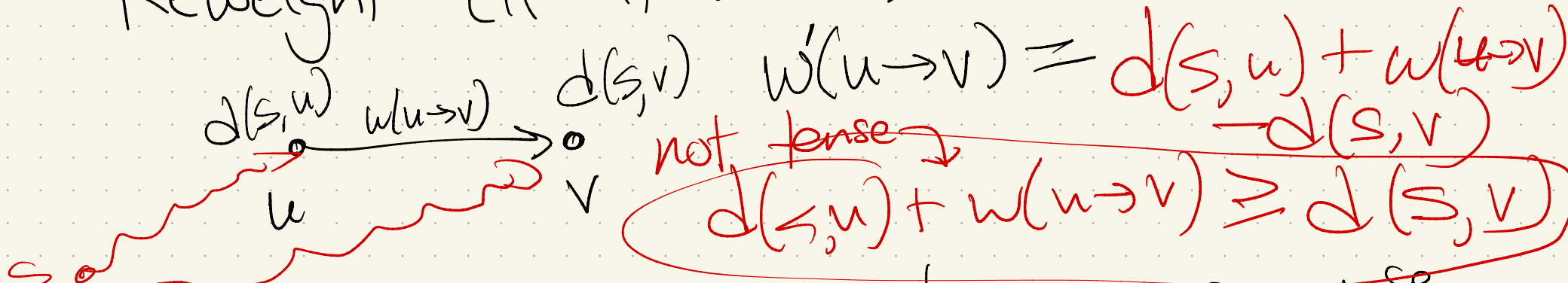
+ blue path: $\pi(s) + \text{original path} - \pi(v)$
 $\pi(s) + \text{original blue} - \pi(v)$

Johnson's algorithm for MSSP:
 use this new kind of weight
 function!

$O(V \cdot E)$

• Run Bellman-Ford once from some $s \in V$
 ↳ no negative cycles or give up
 no tense edges

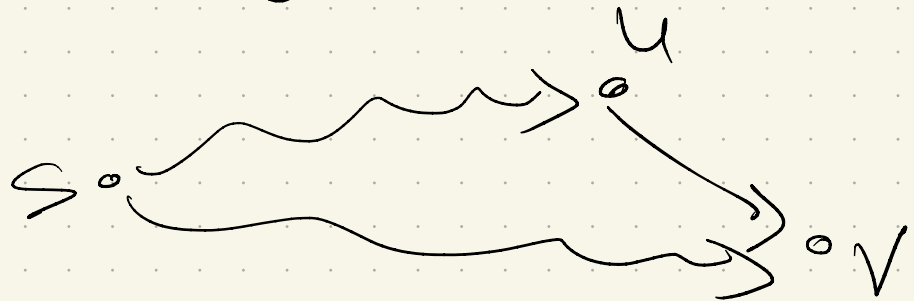
• Reweight (if it works): let $\pi(v) = d(s, v)$



• Now, all paths are positive, so can use
 faster algorithm for other SSSPs!

Aside: Why positive?

After SSSP, no edges are
tense:



$$\text{so } \underline{d(s, u) + w(u \rightarrow v)} \geq \underline{d(s, v)}$$

rearrange:

$$\begin{aligned} \hookrightarrow d(s, u) + w(u \rightarrow v) - d(s, v) \\ = w'(u \rightarrow v) \geq 0 \end{aligned}$$

So - Algorithm:

Runtime:

$$O(VE \log V)$$

$$P: \frac{\pi(s) + (\text{path})}{\text{min}} \Rightarrow -\pi(v)$$

JOHNSONAPSP(V, E, w) :

⟨⟨Add an artificial source⟩⟩

add a new vertex *s*

for every vertex *v*

add a new edge *s*→*v*

$w(s \rightarrow v) \leftarrow 0$

⟨⟨Compute vertex prices⟩⟩

$\text{dist}[s, \cdot] \leftarrow \text{BELLMANFORD}(V, E, w, s)$

if BELLMANFORD found a negative cycle

fail gracefully

⟨⟨Reweight the edges⟩⟩

for every edge *u*→*v* ∈ *E*

$w'(u \rightarrow v) \leftarrow \text{dist}[s, u] + w(u \rightarrow v) - \text{dist}[s, v]$

⟨⟨Compute reweighted shortest path distances⟩⟩

for every vertex *u*

$\text{dist}'[u, \cdot] \leftarrow \text{DIJKSTRA}(V, E, w', u)$

⟨⟨Compute original shortest-path distances⟩⟩

for every vertex *u*

for every vertex *v*

$\text{dist}[u, v] \leftarrow \text{dist}'[u, v] - \text{dist}[s, u] + \text{dist}[s, v]$

Figure 9.2. Johnson's all-pairs shortest paths algorithm

Compare to naive: $O(V^2 E) = O(V^4)$
V vs *log V*

More Improvements

Set up recursive approach:

Let $\text{dist}(u, v, l)$ = best $u \rightsquigarrow v$ path using at most l edges.

Then, back to "keep relaxing edges" approach:



$$\text{dist}(u, v, l) = \begin{cases} 0 & \text{if } l = 0 \text{ and } u = v \\ \infty & \text{if } l = 0 \text{ and } u \neq v \\ \min \left\{ \begin{array}{l} \text{dist}(u, v, l-1) \\ \min_{x \rightarrow v} (\text{dist}(u, x, l-1) + w(x \rightarrow v)) \end{array} \right\} & \text{otherwise} \end{cases}$$

build length l via length $l-1$ do use another edge

don't use another edge

Code:

SHIMBELAPSP(V, E, w):

```
for all vertices u
  for all vertices v
    if u = v
      dist[u, v, 0] ← 0
    else
      dist[u, v, 0] ← ∞
```

} paths of length 0
need V-1 edges

```
for l ← 1 to V - 1
```

```
  for all vertices u
```

```
    for all vertices v ≠ u
```

```
      dist[u, v, l] ← dist[u, v, l - 1]
```

```
      for all edges x → v
```

```
        if dist[u, v, l] > dist[u, x, l - 1] + w(x → v)
```

```
          dist[u, v, l] ← dist[u, x, l - 1] + w(x → v)
```

Can improve

ALLPAIRSBELLMANFORD(V, E, w):

```
for all vertices u
```

```
  for all vertices v
```

```
    if u = v
```

```
      dist[u, v] ← 0
```

```
    else
```

```
      dist[u, v] ← ∞
```

```
for l ← 1 to V - 1
```

```
  for all vertices u
```

```
    for all edges x → v
```

```
      if dist[u, v] > dist[u, x] + w(x → v)
```

```
        dist[u, v] ← dist[u, x] + w(x → v)
```

Runtime:

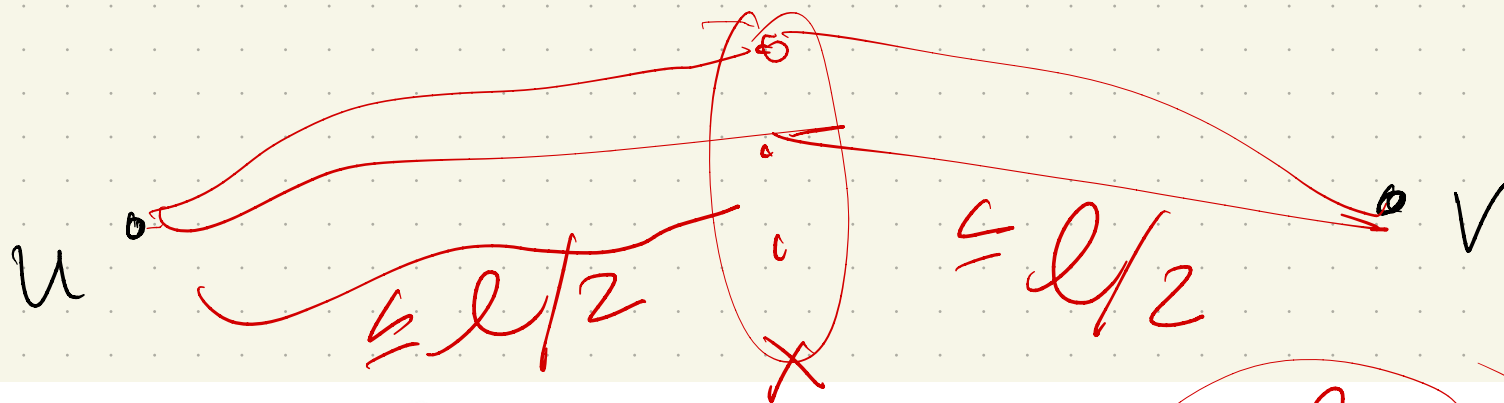
$V^2 E$

$V^2 V^4$

Wait \rightarrow that's worse!

But, let's try a more balanced
divide & conquer!

Instead of going $n-1 \rightarrow n$,
can we add longer paths?



$$\text{dist}(u, v, \underline{l}) = \begin{cases} \underline{w(u \rightarrow v)} & \text{if } \underline{l} = 1 \\ \min_x (\text{dist}(\underline{u}, \underline{x}, \underline{l}/2) + \text{dist}(x, v, \underline{l}/2)) & \text{otherwise} \end{cases}$$

\rightarrow best $u \rightarrow v$ path of
length $\leq l$

Code:

FISCHERMEYERAPSP(V, E, w):

for all vertices u

for all vertices v

$dist[u, v, 0] \leftarrow w(u \rightarrow v)$

for $i \leftarrow 1$ to $\lceil \lg V \rceil$

$\langle\langle l = 2^i \rangle\rangle$

for all vertices u

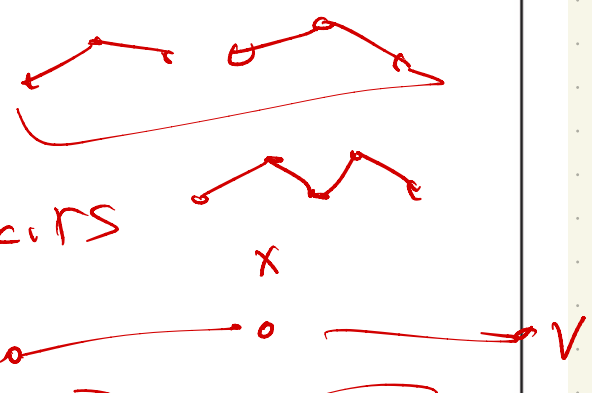
for all vertices v

$dist[u, v, i] \leftarrow \infty$

for all vertices x

if $dist[u, v, i] > dist[u, x, i-1] + dist[x, v, i-1]$

$dist[u, v, i] \leftarrow dist[u, x, i-1] + dist[x, v, i-1]$



all pairs
 $\sqrt{2}$

can also save space

LEYZOREKAPSP(V, E, w):

for all vertices u

for all vertices v

$dist[u, v] \leftarrow w(u \rightarrow v)$

for $i \leftarrow 1$ to $\lceil \lg V \rceil$

$\langle\langle l = 2^i \rangle\rangle$

for all vertices u

for all vertices v

for all vertices x

if $dist[u, v] > dist[u, x] + dist[x, v]$

$dist[u, v] \leftarrow dist[u, x] + dist[x, v]$

$V^3 \log V$

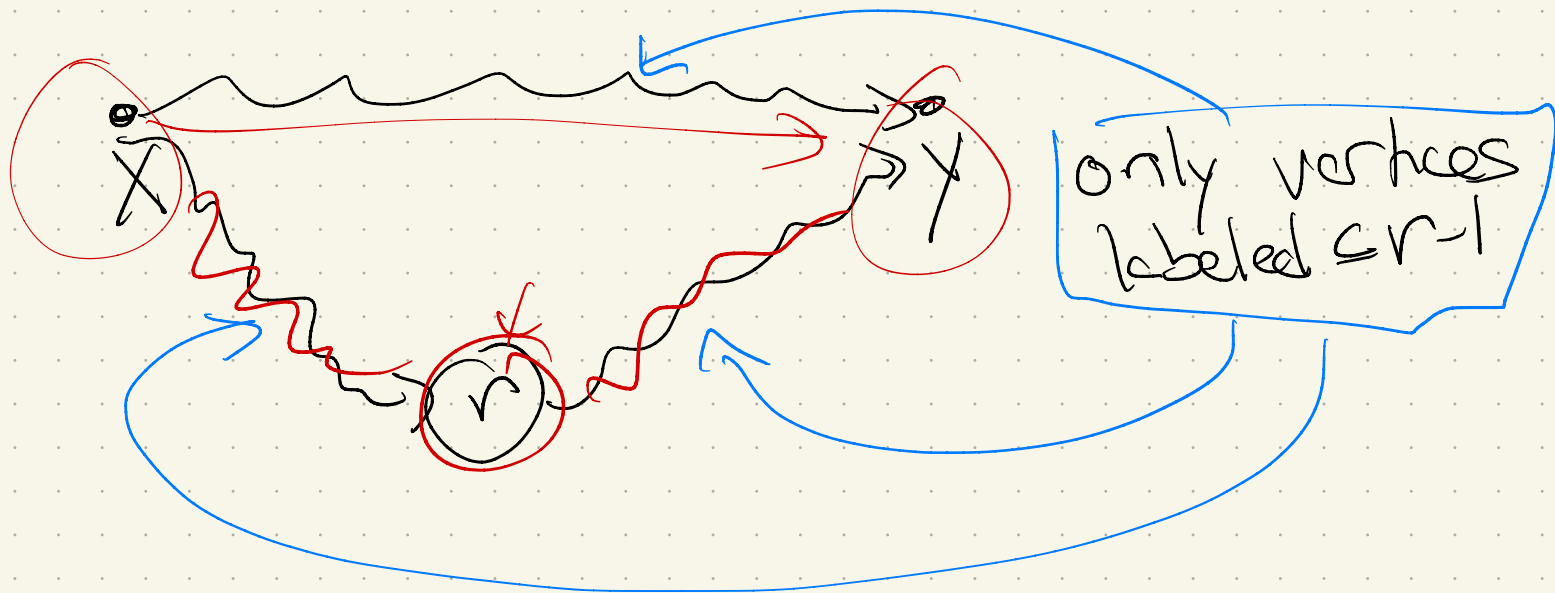
Can we get better?

Floyd-Warshall: order vertices $1, \dots, V$ instead of path length
Does vertex order

Let $d(x, y, r) =$

best length path via
vertices labeled $1 \dots r$

Then:



Recursion:

$$\text{dist}(u, v, r) = \begin{cases} w(u \rightarrow v) & \text{if } r = 0 \\ \min \left\{ \begin{array}{l} \text{dist}(u, v, r - 1) \\ \text{dist}(u, r, r - 1) + \text{dist}(r, v, r - 1) \end{array} \right\} & \text{otherwise} \end{cases}$$

don't use
vertex r

use vertex r

code ~>

KLEENEAPSP(V, E, w):

```
for all vertices  $u$ 
  for all vertices  $v$ 
     $dist[u, v, 0] \leftarrow w(u \rightarrow v)$ 

for  $r \leftarrow 1$  to  $V$ 
  for all vertices  $u$ 
    for all vertices  $v$ 
      if  $dist[u, v, r - 1] < dist[u, r, r - 1] + dist[r, v, r - 1]$ 
         $dist[u, v, r] \leftarrow dist[u, v, r - 1]$ 
      else
         $dist[u, v, r] \leftarrow dist[u, r, r - 1] + dist[r, v, r - 1]$ 
```

Runtime!

save
space



FLOYDWARSHALL(V, E, w):

```
for all vertices  $u$ 
  for all vertices  $v$ 
     $dist[u, v] \leftarrow w(u \rightarrow v)$ 

for all vertices  $r$ 
  for all vertices  $u$ 
    for all vertices  $v$ 
      if  $dist[u, v] > dist[u, r] + dist[r, v]$ 
         $dist[u, v] \leftarrow dist[u, r] + dist[r, v]$ 
```

Next topic: Flows & cuts